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A Novel Image Compression Algorithm for High Resolution 3D Reconstruction

M. M. Siddeq · M. A. Rodrigues

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Abstract This research presents a novel algorithm to compress high-resolution images for accurate structured light 3D reconstruction. Structured light images contain a pattern of light and shadows projected on the surface of the object, which are captured by the sensor at very high resolutions. Our algorithm is concerned with compressing such images to a high degree with minimum loss without adversely affecting 3D reconstruction. The Compression Algorithm starts with a single level discrete wavelet transform (DWT) for decomposing an image into four sub-bands. The sub-band LL is transformed by DCT yielding a DC-matrix and an AC-matrix. The Minimize-Matrix-Size Algorithm is used to compress the AC-matrix while a DWT is applied again to the DC-matrix resulting in LL_2 , HL_2 , LH_2 and HH_2 sub-bands. The LL_2 sub-band is transformed by DCT, while the Minimize-Matrix-Size Algorithm is applied to the other sub-bands. The proposed algorithm has been tested with images of different sizes within a 3D reconstruction scenario. The algorithm is demonstrated to be more effective than JPEG2000 and JPEG concerning higher compression rates with equivalent perceived quality and

the ability to more accurately reconstruct the 3D models.

Keywords DWT · DCT · Minimize-Matrix-Size · LSS-Algorithm · 3D reconstruction

1 Introduction

The researches in compression techniques has stemmed from the ever-increasing need for efficient data transmission, storage and utilization of hardware resources. Uncompressed image data require considerable storage capacity and transmission bandwidth. Despite rapid progresses in mass storage density, processor speeds and digital communication system performance demand for data storage capacity and data transmission bandwidth continues to outstrip the capabilities of available technologies [2]. The recent growth of data intensive multimedia based applications have not only sustained the need for more efficient ways to encode signals and images but have made compression of such signals central to signal storage and digital communication technology [7].

Compressing an image is significantly different from compressing raw binary data. It is certainly the case that general purpose compression programs can be used to compress images, but the result is less than optimal. This is because images have certain statistical properties that can be exploited by encoders specifically designed for them [7, 10]. Also, some of the finer

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details in the image can be sacrificed for the sake of saving a little more bandwidth or storage space. Lossless compression is involved with compressing data which, when decompressed, will be an exact replica of the original data. This is the case when binary data such as executable documents are compressed [13]. They need to be exactly reproduced when decompressed. On the other hand, images need not be reproduced ‘exactly’. An approximation of the original image is enough for most purposes, as long as the error between the original and the compressed image is tolerable [9].

The neighbouring pixels in most images are highly correlated and therefore hold redundant information. The foremost task then is to find out less correlated representation of the image. Image compression is actually the reduction of the amount of this redundant data (bits) without degrading the quality of the image to an unacceptable level. There are mainly two basic components of image compression—redundancy reduction and irrelevancy reduction [16]. The redundancy reduction aims at removing duplication from the signal source image while the irrelevancy reduction omits parts of the signal that is not noticed by the signal receiver i.e., the Human Visual System (HVS) which presents some tolerance to distortion, depending on the image content and viewing conditions. Consequently, pixels must not always be regenerated exactly as originated and the HVS will not detect the difference between original and reproduced images [3].

The current standards for compression of still image (e.g., JPEG) use Discrete Cosine Transform (DCT), which represents an image as a superposition of cosine functions with different discrete frequencies. The DCT can be regarded as a discrete time version of the Fourier Cosine series. It is a close relative of Discrete Fourier Transform (DFT), a technique for converting a signal into elementary frequency components. Thus, DCT can be computed with a Fast Fourier Transform (FFT) like algorithm of complexity $O(n \log_2 n)$ [8]. More recently, the wavelet transform has emerged as a cutting edge technology within the field of image analysis. The wavelet transformations have a wide variety of different applications in computer graphics including radiosity, multi-resolution painting, curve design, mesh optimization, volume visualization, image searching and one of the first applications in computer graphics, image compression

[15]. The Discrete Wavelet Transform (DWT) provides adaptive spatial frequency resolution (better spatial resolution at high frequencies and better frequency resolution at low frequencies) that is well matched to the properties of a HVS [6, 7].

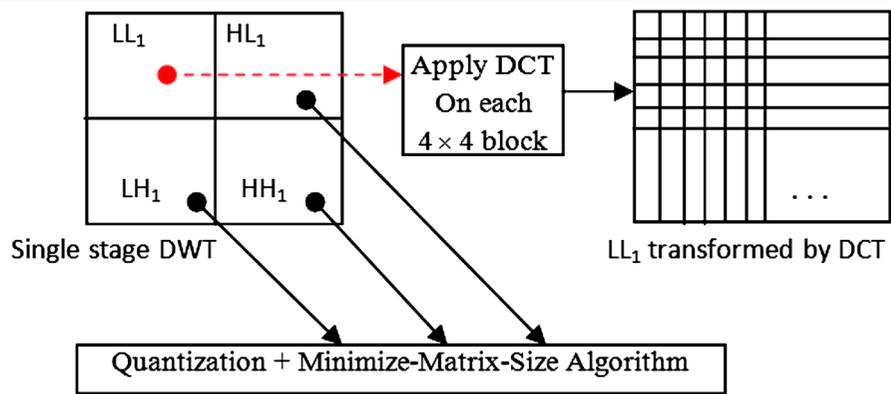
Here a further requirement is introduced concerning the compression of 3D data. We demonstrated that while geometry and connectivity of a 3D mesh can be tackled by a number of techniques such as high degree polynomial interpolation [11] or partial differential equations [12], the issue of efficient compression of 2D images both for 3D reconstruction and texture mapping for structured light 3D applications has not been addressed. Moreover, in many applications, it is necessary to transmit 3D models over the Internet to share CAD/CAM models with e-commerce customers, to update content for entertainment applications, or to support collaborative design, analysis, and display of engineering, medical, and scientific datasets. Bandwidth imposes hard limits on the amount of data transmission and, together with storage costs, limit the complexity of the 3D models that can be transmitted over the Internet and other networked environments [12].

It is envisaged that surface patches can be compressed as a 2D image together with 3D calibration parameters, transmitted over a network and remotely reconstructed (geometry, connectivity and texture map) at the receiving end with the same resolution as the original data. The widespread integration of 3D models in different fields motivates the need to be able to store, index, classify, and retrieve 3D objects automatically and efficiently. In the following sections we describe a novel algorithm that can robustly achieve the aims of efficient compression and accurate 3D reconstruction.

2 The Proposed Compression Algorithm

The proposed image compression method depends on the single level DWT, which decomposes an image into approximation coefficients (LL) and high frequency domains (LH, HL and HH). The LL matrix is divided into non-overlapping blocks of data of 4×4 pixels that are transformed by DCT producing a DC-matrix and an AC-matrix. The AC-matrix contains the high frequency sub-bands and is coded by the Minimize-Matrix-Size Algorithm while the DC-matrix is

Fig. 2 LL₁ sub-band transformed by DCT for each 4 × 4 block set



where

$$a(u) = \sqrt{\frac{1}{N}}, \quad \text{for } u = 0$$

$$a(u) = \sqrt{\frac{2}{N}}, \quad \text{for } u \neq 0$$

$$f(x,y) = \sum_{u=0}^{N-1} \sum_{v=0}^{N-1} a(u)a(v)C(u,v) \cos\left[\frac{(2x+1)u\pi}{2N}\right] \times \cos\left[\frac{(2y+1)v\pi}{2N}\right] \quad (2)$$

One of the key differences between the applications of the DWT and Discrete Cosine transformation (DCT) is that the DWT is typically applied to an image as a one block or a large rectangular region of the image, while DCT is used for small block sizes. The DCT becomes increasingly complicated to calculate for larger blocks, for this reason in this research a 4 × 4 pixel block is used, whereas a DWT will be more efficiently applied to the complete images yielding good compression ratios [16].

Each 4 × 4 coefficients from LL₁ are divided by a quantizing factor *Q*, using matrix-dot-division. This process is called *quantization*, which removes insignificant coefficients and increasing the zeros in LL₁. The factor *Q* can be computed as follows:

$$L = \text{Quality} \times \max(LL1) \quad (3)$$

$$Q(i,j) = \begin{cases} 10, & i, j = 1 \\ L + i + j, & i > 1 \end{cases} \quad (4)$$

Note *i, j = 1, 2, 3, 4*

The parameter *L* in Eq. (3) is computed from the maximum value in the LL₁ sub-band, and “Quality” value ≥ 0.01. The quality value is represented as a ratio

for maximum value, if this ratio increased this leads to larger number of coefficients being forced to zero leading thus, to lower image quality. Each DC value from 4 × 4 block is stored in a different matrix called the DC-matrix, and other AC coefficients ((4 × 4) – 1) are stored in the AC-matrix. The other high frequency sub-bands (HL₁, LH₁ and HH₁) are quantized by Eq. (3) and coded by the Minimize-Matrix-Size Algorithm.

The DC-matrix transformed by single level DWT to produce further sub-bands LL₂, LH₂, HL₂ and HH₂. The LL₂ quantized by divide each value in the matrix by “2”. This is because to reduce bit size. Similarly, the other high frequency sub-bands values are quantized either by “2”, for normalize high-frequencies, also increasing number of zeros.

The LL₂ is transformed by using one-dimensional DCT for each 4 items of data (i.e. assume *u = 0, v = 0* to converting two dimensional DCT into one dimensional DCT), and then truncate each value. This means that one should not use scalar quantization at this stage.

The next step takes the difference between two neighbour values for each column in LL₂. This process is called DBV (Difference Between two Values), which is based on the well-known fact that neighbouring coefficients in the LL₂ are correlated. Correlated values are generally similar, so their differences are small and more data will be repeated, this will be very easy for compression. Eq. (5) represents DBV for each column in LL₂. Figure 3 illustrates the DBV.

$$D(i) = D(i) - D(i + 1) \quad (5)$$

where *i = 1, 2, 3, ..., m – 1* and *m* is the column size of LL₂.

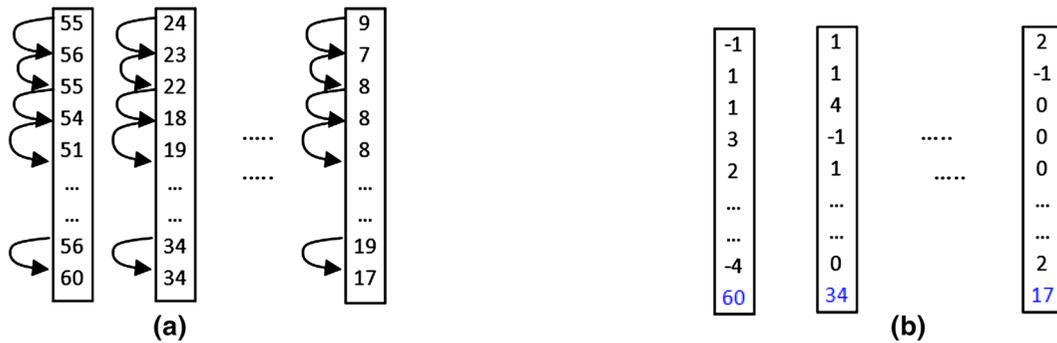


Fig. 3 **a** A matrix before DBV, **b** apply DVB between two neighbors in each column

2.3 Compress Data by Minimize-Matrix-Size Algorithm

This algorithm is used to reduce the size of the AC-matrix and other high frequency sub-bands. It depends on the *Random-Weight-Values* and three coefficients to calculate and store values in a new array. The following List-1 describes the steps in the Minimize-Matrix-Size-Algorithm:

List-1 Minimize-Matrix-Size Algorithm

```

Let K=3                                     %% take each three coefficients from a matrix
W=Generate-Ransom-Weights (K)             %% generate three random weights values according
                                           %% to the number of coefficients

Let p=1
For i=1 to column size
  For j=1 to row size
    Intermediate [p]=Matrix[i,j]          %% Scan row-by-row
    p++
  End
End

Let j=1; p=1
While (j<row size*column size)
  Arr=Read_K_coefficients (Intermediate [j])
  
$$M(p) = \sum_{i=1}^K W(i) * Arr(i)$$

  j=j+k
  p++
End

```

In the above List-1 the weight values are generated randomly (i.e. random numbers in the range = {0...1}) multiplied with $Arr(i)$ (i.e. represents three coefficients from a matrix) to produce minimized array $M(p)$. The algorithm in List-1 is applied to each sub-band independently; this means each minimized

sub-band is independently compressed. Figure 4 illustrates the Minimize-Matrix-Size Algorithm applied to a matrix.

Before applying the Minimize-Matrix-Size Algorithm, our compression algorithm computes the probability of the data for each high frequency matrix. These probabilities are called Limited-Data, which is used later in the decompression stage. The Limited-Data is stored as a header in the compressed file and

are not subject to compression. Figure 5 illustrates the probability of data in a matrix.

The final step in our compression algorithm is *Arithmetic coding*, which takes a stream of data and convert it into a one-dimensional floating-point values. These output values lie in the range between zero

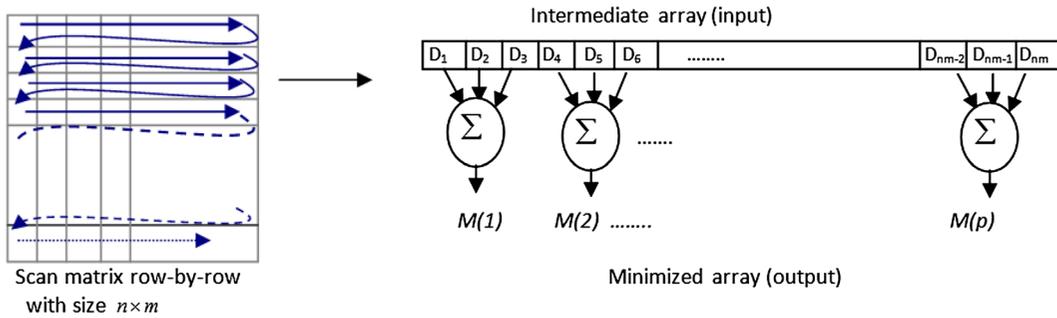


Fig. 4 An $n \times m$ matrix is minimized into an array M

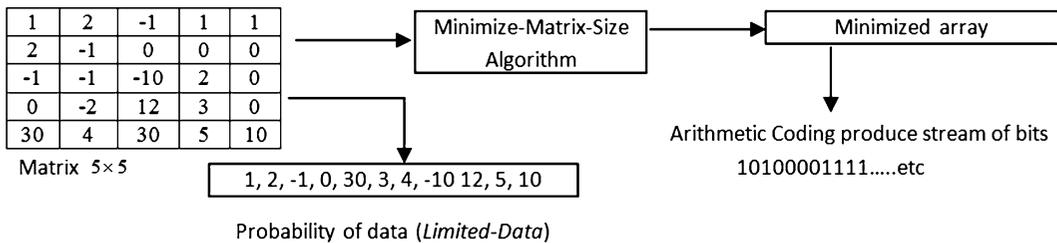


Fig. 5 The limited-data for a 5×5 matrix is illustrated as a list of probabilities and the minimized array is subject to arithmetic coding

and one and, when decoded, should reproduce the exact original stream of data. The arithmetic coding needs to compute the probability of all data and assign a range for each, the ranges are limited between Low and High values.

3 The Decompression Algorithm

The decompression algorithm is the inverse of compression. The first stage is to decode the minimized array by arithmetic decoding then the *Limited Sequential Search Algorithm* (LSS-Algorithm) is used to decode each sub-band independently. The LSS-Algorithm depends on the *Limited-Data* array. If the limited data are missed or destroyed, the image could be degraded or damaged. Figure 6 shows the decompression method in a flowchart style.

The LSS-Algorithm is designed to find the original data inside a limited data set, by using three pointers. These pointers refer to positions in the Limited-Data matrix. The initial values of these pointers are 1 (i.e. first location in the Limited-Data matrix). These three pointers are called $S1$, $S2$ and $S3$ and are incremented by one in a cogwheel fashion (e.g. similar to a clock, where $S1$, $S2$ and $S3$ represent hour, minutes and

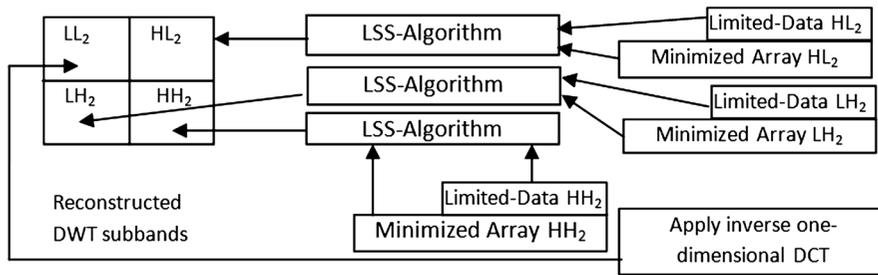
seconds respectively). To illustrate the LSS-Algorithm assume that we have the following 2×3 matrix:

30	1	0
19	1	1

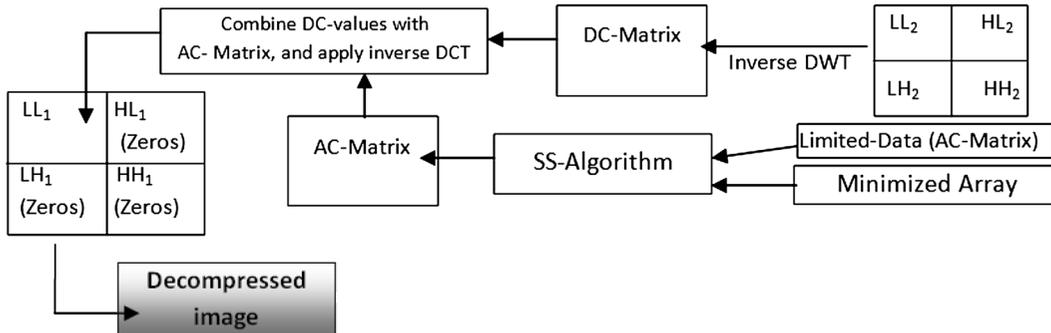
The above matrix will compress by using Minimize-Matrix-Size Algorithm to produce a minimized array $M(1) = 3.65$ and $M(2) = 2.973$, Limited-Data = $\{30, 19, 1, 0\}$ and Random-Weight-Values = $\{0.1, 0.65, \text{ and } 0.423\}$. Now the LSS-Algorithm will return the original values for the above 2×3 matrix by using the Limited-Data and the random-weight-values. The first step in the decompression algorithm assigns $S1 = S2 = S3 = 1$, then compute the result of the following equation:

$$Est = W(1) \times Limited(S1) + W(2) \times Limited(S2) + W(3) \times Limited(S3) \tag{6}$$

where W is the generated weights and *Limited* is the Limited-Data matrix. The LSS-Algorithm computes *Est* at each iteration, and compares with $M(i)$. If it is zero, the estimated values are found at locations = $\{S1, S2 \text{ and } S3\}$ according to Limited-Data.



(a) First Stage Decompression algorithm for reconstruct DWT subbands (LL₂, LH₂, HL₂ and HH₂)



(b) Second stage Decompression algorithm for reconstruct LL₁ (decompressed image)

Fig. 6 A two-stage decomposition algorithm is depicted in (a) and (b)

If not, the algorithm will continue to find the original values. This process continues until the end of minimizing array M(I). The algorithm in List-2 illustrates the LSS-Algorithm.

After the high frequency sub-bands are decoded by the LSS-Algorithm, the next step in the decompression algorithm is to apply ABV (Addition between two Values) on the decoded LL₂ to return the original

List-2 LSS-Algorithm

```

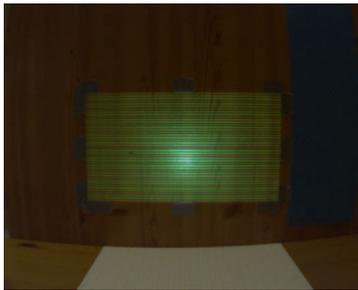
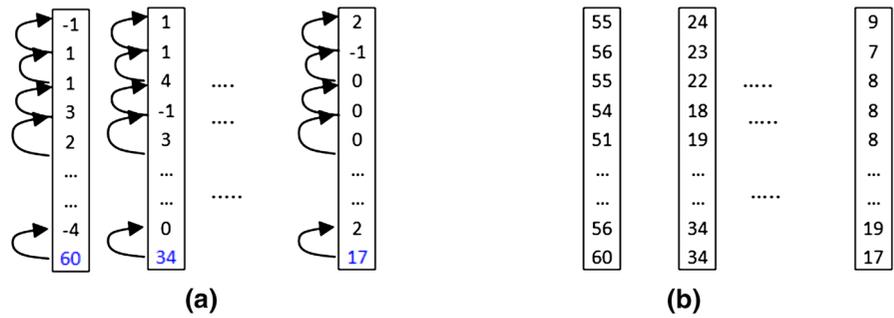
Let Limited [1...m]           %% represents Limited Data
Let M [1...p]                 %% represents minimized array with size p
Let K=3                       %% number of estimated coefficients

For i=1 to p
  S1=1; S2=1; S3=1           %% initial location
  Iterations=1
  Est=W(1)*Limited[S1] + W(2)*Limited[S2]+W(3)*Limited[S3]

  While ( (M(i) - Est) ≠ 0)   %% check if Error =0 or not
    S3++                       %% increment pointer represents "Seconds"
    IF (S3>m) S2++; S3=1 end;  %% check if S3 is over the limit, return back to "1", and increment S2
    IF (S2>m) S1++; S2=1 end;
    IF (S1>m) S1=1;           end;
    Est=W(1)*Limited[S1] + W(2)*Limited[S2]+W(3)*Limited[S3]; %% compute Est after increments
    Iterations++             %% compute number of iterations
  End                         %% end of while
End

```

Fig. 7 **a** A matrix before apply ABV, **b** apply ABV between two neighbours in each column



(a) 2D BMP “Wall”, dimension 1280x1024 pixels, size=3.75 Mbytes



(b) 2D BMP “Girl”, dimension 1392x1040 pixels, size=4.14 Mbytes



(c) 2D BMP “Woman”, 1392x1040 pixels, size=4.14 Mbytes

Fig. 8 **a** 2D colour BMP image, **b–c** 2D *grey scale* images

Table 1 Compressed image sizes using high frequencies in first level DWT

Image name	Original size (MB)	Compressed size (KB)	Quantization values	
			Low-frequency	High-frequency
Wall	3.75	74	0.02	0.02
Wall	3.75	47.6	0.04	0.04
Wall	3.75	33.7	0.08	0.08
Girl	4.14	78	0.02	0.02
Girl	4.14	48	0.04	0.04
Girl	4.14	29.1	0.08	0.08
Woman	4.14	62.1	0.02	0.02
Woman	4.14	38.1	0.04	0.04
Woman	4.14	24.5	0.08	0.08

Table 2 Compressed image size without using high-frequencies in first level DWT

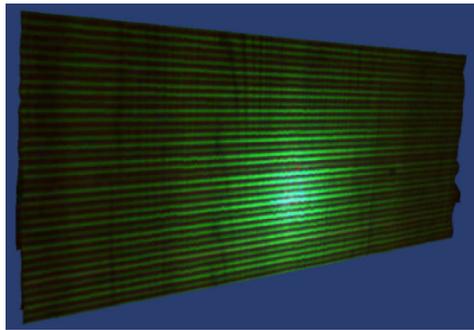
Image name	Original size (MB)	Compressed size (KB)	Quantization values	
			Low-frequency	High-frequency
Wall	3.75	62	0.02	Ignored
Wall	3.75	45	0.04	Ignored
Wall	3.75	33.5	0.08	Ignored
Girl	4.14	61.2	0.02	Ignored
Girl	4.14	42.6	0.04	Ignored
Girl	4.14	28.3	0.08	Ignored
Woman	4.14	53.4	0.02	Ignored
Woman	4.14	35.4	0.04	Ignored
Woman	4.14	24.3	0.08	Ignored

values. ABV represents an inverse equation for DBV (See Eq. 5). ABV is applied on each column, which takes the last value at position m , and add it to the previous value, and then the total adds to the next previous value and so on. The following equation defines the ABV decoder.

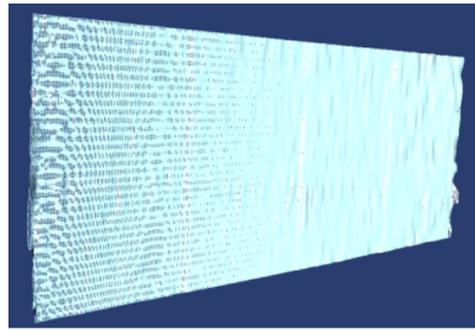
$$D(i - 1) = D(i - 1) + D(i) \tag{7}$$

where $i = m, (m - 1), (m - 2), (m - 3), \dots, 2$

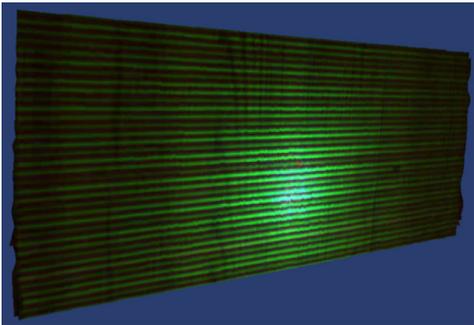
Then the inverse one-dimensional DCT is applied to each 4 items of data from LL_2 . Recomposing LL_2 , HL_2 , HL_2 and HH_2 by inverse DWT yields an approximation of the original DC-matrix. Next, combine each DC value from the DC-matrix with each $([4 \times 4] - 1)$ block from the AC-matrix to generate



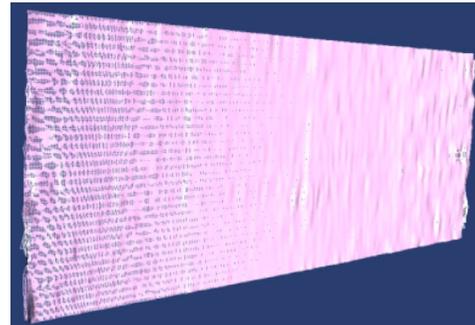
(a) 3D Wall textured, Quality=0.02



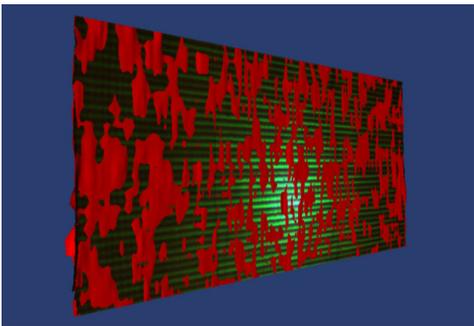
3D Wall shaded, Quality = 0.02



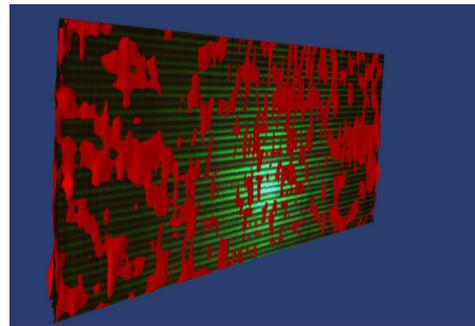
(b) 3D Wall textured, Quality = 0.04



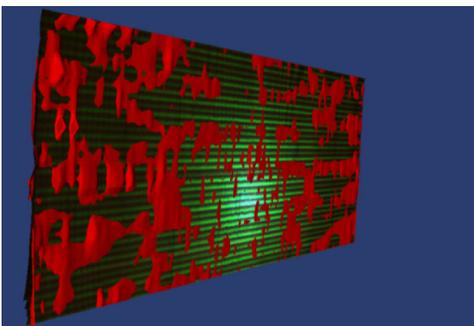
3D Wall shaded, Quality = 0.04



(c) 3D Wall shaded (red) compared to original (textured), Quality = 0.02



3D Wall shaded (red) compared to original (textured), Quality = 0.04

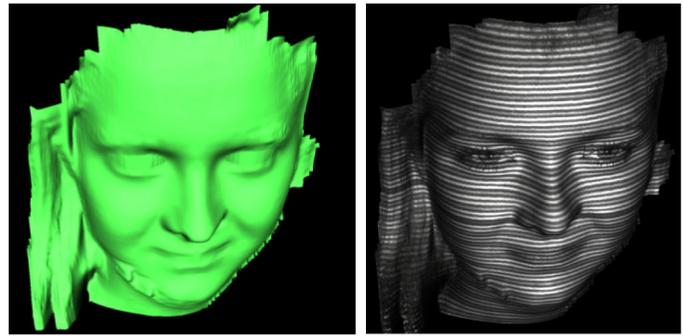


(d) 3D Wall shaded (red) compared to original (textured), Quality = 0.08

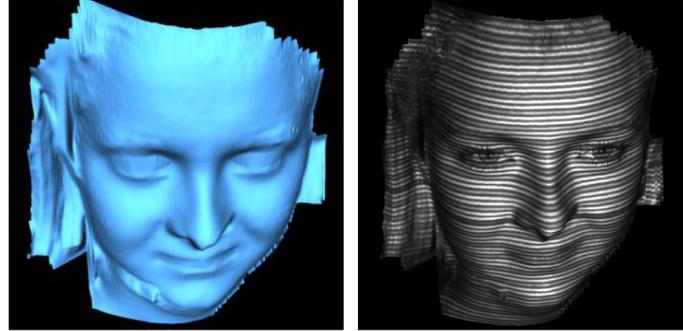
Fig. 9 a and b 3D decompressed image of wall with different quality values. c, d and e Differences between original 3D wall image and decompressed 3D wall image according to quality

parameter. Red regions represent the 3D wall decompressed image matched with the background original 3D Wall image in three cases, i.e., high, median and low quality parameters. (Color figure online)

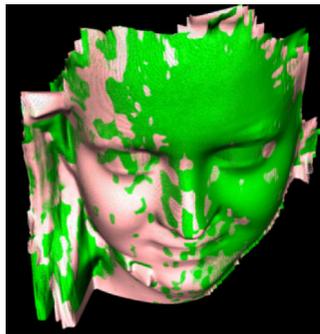
Fig. 10 **a** and **b** 3D decompressed girl image with different quality values. **c**, **d** and **e** Differences between original 3D girl image and decompressed 3D girl image according to quality parameters. The *pink* model represents the original background 3D image, while *other colour* represents the 3D decompressed image with various quality parameters. (Color figure online)



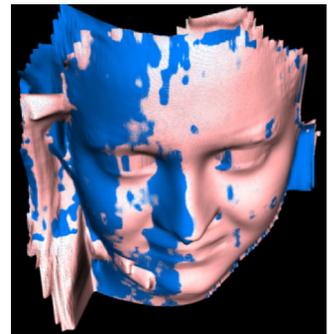
(a) 3D Girl image texture and shaded, Quality=0.02



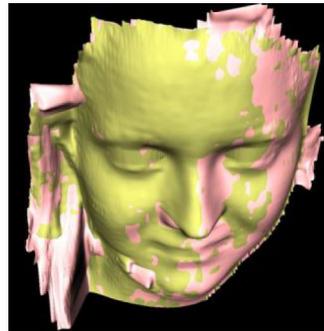
(b) 3D Girl image shaded and texture, Quality=0.04



(c) Quality=0.02

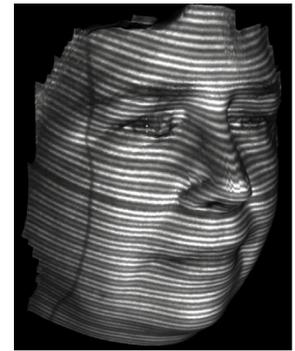
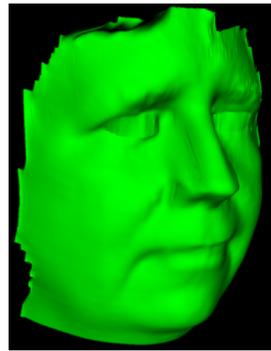


(d) Quality=0.04

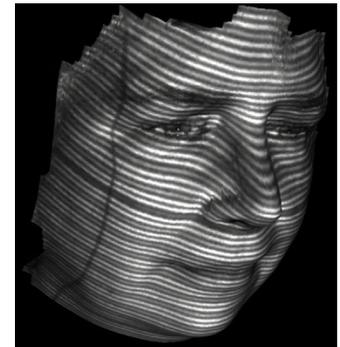
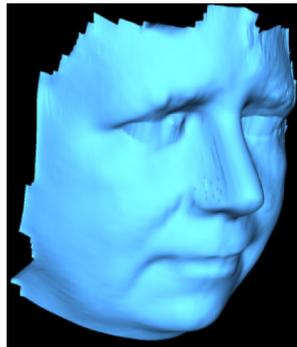


(e) Quality=0.08

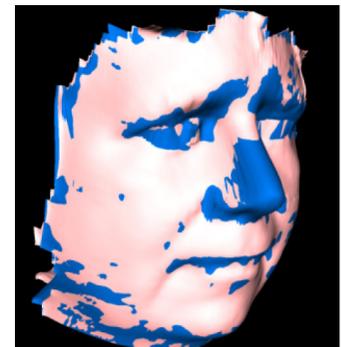
Fig. 11 **a** and **b** 3D decompressed woman image with different quality values. **c**, **d** and **e** Differences between original 3D woman image and decompressed 3D woman image according to quality parameters. The *pink* model is the original 3D woman model while *blue*, *green*, and *golden* models refer to high, median and low image quality respectively. (Color figure online)



(a) 3D Woman image shaded and texture, Quality=0.02

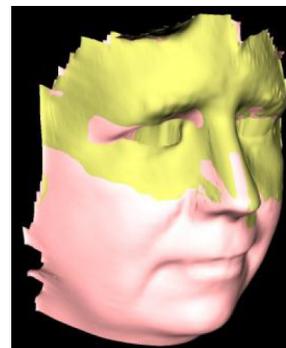


(b) 3D Woman image shaded and texture, Quality=0.04



(c) Quality=0.02

(d) Quality=0.04



(e) Quality=0.08

Table 3 PSNR and MSE between original and decompressed 2D images

Image name	RMSE	3D RMSE	Quantization values	
			Low-frequency	High-frequency
Wall	2.49	2.09	0.02	0.02
Wall	2.82	3.95	0.04	0.04
Wall	3.25	4.72	0.08	0.08
Girl	3.09	3.78	0.02	0.02
Girl	4.08	3.94	0.04	0.04
Girl	5.25	3.66	0.08	0.08
Woman	2.88	3.37	0.02	0.02
Woman	3.53	3.09	0.04	0.04
Woman	4.35	2.61	0.08	0.08

Image name	MSE	3D RMSE	Quantization values	
			Low-frequency	High-frequency
Wall	2.66	2.09	0.02	Ignored
Wall	2.86	3.95	0.04	Ignored
Wall	3.24	4.72	0.08	Ignored
Girl	4.39	3.41	0.02	Ignored
Girl	4.71	3.83	0.04	Ignored
Girl	5.34	3.74	0.08	Ignored
Woman	3.38	3.12	0.02	Ignored
Woman	3.73	3.07	0.04	Ignored
Woman	4.38	2.71	0.08	Ignored

Table 4 Comparison between the proposed algorithm and JPEG2000 and JPEG techniques

Image name	Quality	Proposal method		JPEG2000		JPEG		Compressed size (Kbytes)
		RMSE	3D RMSE	RMSE	3D RMSE	RMSE	3D RMSE	
Wall	High	2.49	2.09	1.92	4.28	3.14	2.8	74
	Median	2.82	3.95	2.14	5.01	3.87	4.5	47.6
	Low	3.25	4.72	2.42	3.52	5.34	6.9	33.7
Girl	High	3.09	3.78	2.14	3.94	3.28	3.94	78
	Median	4.08	3.94	2.88	4.02	4.72	3.72	48
	Low	5.25	3.66	Non	Non	Non	Non	29.1
Woman	High	2.88	3.37	2.14	3.14	2.6	2.55	62.1
	Median	3.53	3.09	2.7	3.2	4.58	2.75	38.1
	Low	4.35	2.61	Non	Non	Non	Non	24.5

the matrix LL_1 , and then apply the inverse quantization followed by the inverse two-dimensional DCT on each 4×4 block from the LL_1 . The result is the reconstructed LL_1 sub-band (Fig. 7).

4 Experimental Results in 2D and 3D

The results described below used Matlab for 2D image compression in connection with a purpose-built 3D

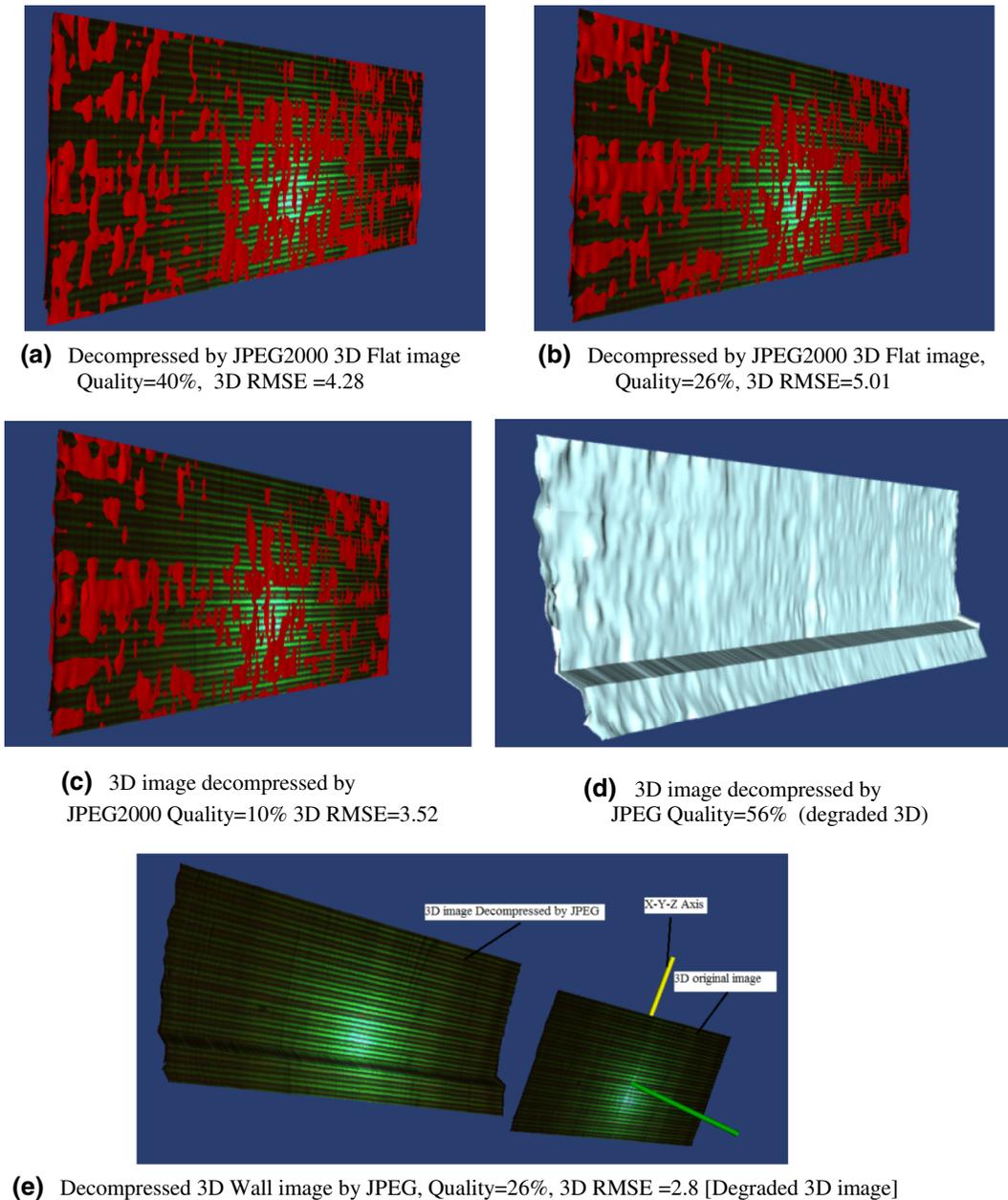


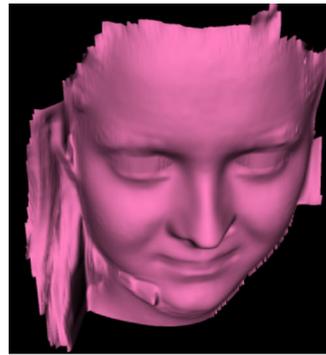
Fig. 12 **a, b** and **c** Decompressed 3D Wall image by JPEG2000, Decompressed image with quality = 40 % most of regions are matched with the original image, similarly in quality = 26 % and quality = 10 % approximately matched

visualization software running on an AMD quad-core microprocessor. In this research we used three types of images with different dimensions. Our compression algorithm is applied to 2D BMP images. Figure 8 shows images tested by our approach, and Table 1 shows the compressed size for each image.

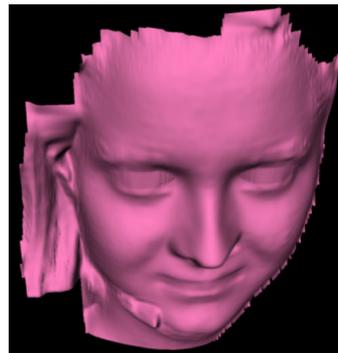
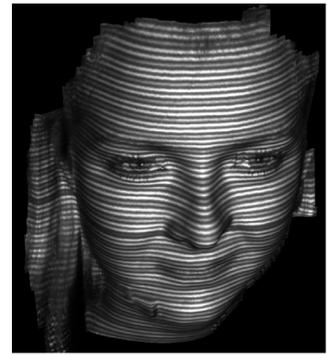
with the original image. **d, e** Decompressed 3D Flat image by JPEG (degraded) un-recognized with original image. Median quality 2D decompressed image by JPEG at quality = 51 %, quality = 23 % non-capable of generating 3D model

The values “0.02”, “0.04” and “0.08” refers to high, median and low quality respectively. These values are used by quantization equation (See Eq. 3) to keep high-frequency coefficients (LH1, HL1 and HH1) at first level DWT. If Quality = 0.02, this means most of the data remains, otherwise, partial data

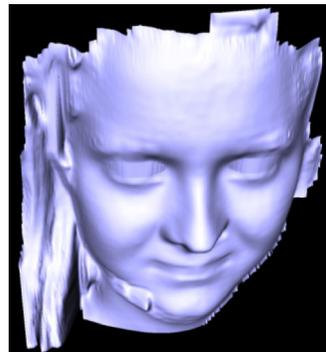
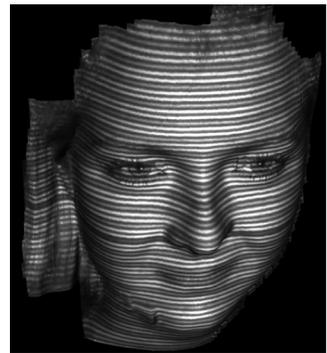
Fig. 13 **a** and **b** Decompressed 3D girl image by JPEG2000. **c**, **d** Decompressed 3D girl image by JPEG. For low quality, JPEG cannot reach to compress size 29.1 Kbytes



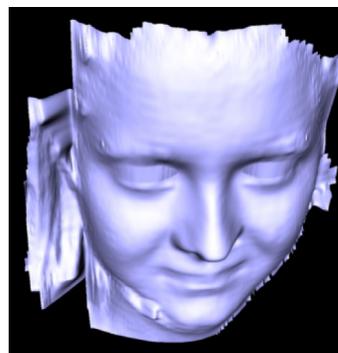
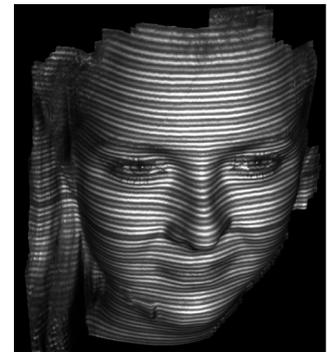
(a) Decompressed 3D image by JPEG2000, Quality=41%, 3D RMSE=3.94



(b) Decompressed 3D image by JPEG2000, Quality=21%, 3D RMSE=4.02



(c) Decompressed 3D image by JPEG, Quality=45%, 3D RMSE=3.94



(d) Decompressed 3D image by JPEG, Quality=17%, 3D RMSE=3.72

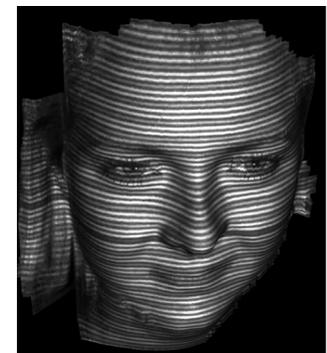
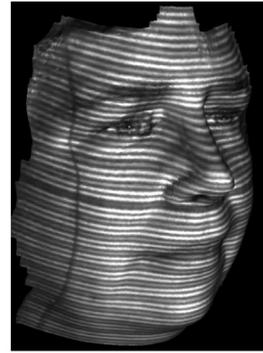
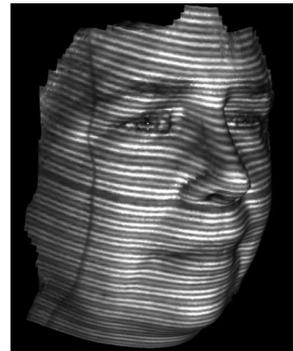
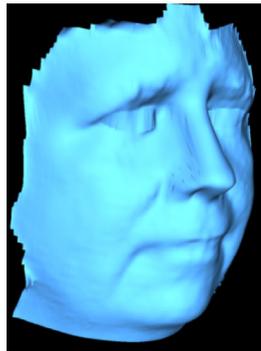


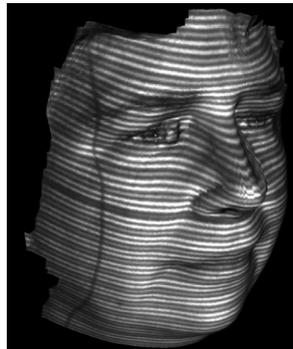
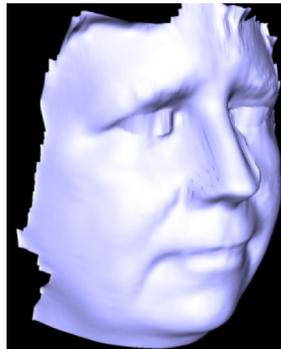
Fig. 14 **a** and **b** Decompressed women image by JPEG2000. **c**, **d** Decompressed 3D women image by JPEG. For low quality JPEG cannot reach to compress size 24.5 Kbytes



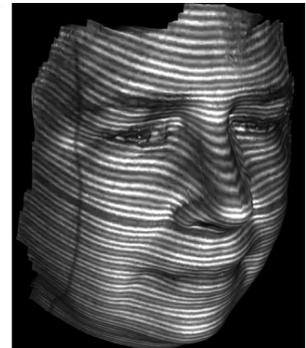
(a) Decompressed 3D image by JPEG2000, Quality=32%, 3D RMSE=3.14



(b) Decompressed 3D image by JPEG2000, Quality=10%, 3D RMSE=3.2



(c) Decompressed 3D image by JPEG, Quality=56%, 3D RMSE=2.55,



(d) Decompressed 3D image by JPEG, Quality=13%, 3D RMSE=2.75

in high frequency sub-bands are discarded, while the low-frequency sub-band depends on the DCT coefficients. Table 2 shows the effects of high frequencies if ignored from the first level DWT decomposition (i.e. all high coefficients values are set to zero).

The proposed image compression algorithm is applied using a range of quality factors (compression rates) and the recovered images are used for 3D reconstruction and compared to the original 3D models. Figures 9, 10 and 11 show the 3D decompressed and 3D reconstructed Wall, Girl and Woman respectively. Table 3 shows the PSNR and MSE for each 2D decompressed image. Peak Signal to Noise Ratio (PSNR) and Mean Square Error (MSE) are used to refer to image quality mathematically. PSNR based on MSE is a very popular quality measure, and can be calculated very easily between the decompressed image and the original image [10, 15].

5 Comparison with JPEG2000 and JPEG Compression Techniques

Our approach is compared with JPEG and JPEG2000; these two techniques are used widely in digital image compression, especially for image transmission and video compression. The JPEG technique is based on the 2D DCT applied on the partitioned image into 8×8 blocks, and then each block encoded by RLE and Huffman encoding [5]. The JPEG2000 is based on the multi-level DWT applied on the partitioned image and then each partition quantized and coded by Arithmetic encoding [1]. Most image compression applications allow the user to specify a quality parameter for the compression. If the image quality is increased the compression ratio is decreased and vice versa [15]. The comparison is based on the 2D image and 3D image quality for test the quality by Root-Mean-Square-Error (RMSE). Table 4 shows the comparison between the three methods.

In the above Table 4 “High” or “Median” means parameters used by each method is different. Also the “NON” refers JPEG2000 and JPEG method cannot reach to the compress size reached by our approach and still be able to reconstruct the model in 3D. Figures 12, 13 and 14 show the 3D decompressed images by JPEG2000 and JPEG.

6 Conclusion

This research has presented and demonstrated a new method for image compression used in 3D applications. The method is based on the transformations (DWT and DCT) and the proposed Minimize-Matrix-Size Algorithm. The results show that our approach introduces better image quality at higher compression ratios than JPEG2000 and JPEG being capable of accurate 3D reconstructing even with very high compression ratios. On the other hand, it is more complex than JPEG2000 and JPEG. The most important aspects of the method and their role in providing high quality compression with high compression ratios are discussed as follows.

1. Using two transformations, this helped our compression algorithm to increase the number of high-frequency coefficients leading to increased compression ratios.
2. The Minimized-Matrix-Size Algorithm is used to collect each three coefficients from the high-frequency matrices, to be single floating-point values. This process converts a matrix into an array, leading to increased compression ratios while keeping the quality of the high-frequency coefficients.
3. The properties of the Daubechies DWT (db3) help the approach for obtaining higher compression ratios. This is because the Daubechies DWT family has the ability to zoom-in onto an image, and the high-frequencies sub-bands of the first level decomposition can be discarded (See Table 3).
4. The LSS-Algorithm represents the core of our decompression algorithm, which converts a one-dimensional array to a matrix, and depends on the Random-Weight-Values. Also, the LSS-Algorithm represents lossless decompression, due to the ability of the Limited-Data to find the exact original data.
5. The Random-Weight-Values and Limited-Data are the keys for coding and decoding an image, without these keys images cannot be reconstructed.
6. Our approach gives better visual image quality compared to JPEG and JPEG2000. This is because our approach removes most of the block artifacts caused by the 8×8 two-dimensional DCT of the JPEG technique [15]. Also our

approach removes some blurring caused by multi-level DWT in JPEG2000 [15].

- The one-dimensional DCT with size $n = 4$, is more efficient than $n = 8$ of JPEG; this helped our decompression approach to obtain better image quality than JPEG.

Also this research has a number of disadvantages illustrated as follows:

- The overall complexity of our approach leads to increased execution time for compression and decompression; the LSS-Algorithm iterative method is particularly complex.
- The compressed header data contain floating-point arrays, thereby causing some increase in compressed data size.

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